

Critical Threshold Phenomena in 1D pressureless Euler-Poisson systems with variable background

Manas Bhatnagar

CAM Seminar, Iowa State University

Oct 5, 2020

This is joint work with my advisor, Dr Hailiang Liu.



This presentation is based on our paper, published in:

Physica D: Nonlinear Phenomena, (414), '20.

Precursor: Critical Thresholds in one dimensional damped Euler-Poisson systems, *Math. Mod. Meth. Appl. Sci.*, 30(5): 891-916, 2020.

Under review: Critical thresholds in a nonlocal Euler system with relaxation, *Submitted in Journal of Differential Equations*

Introduction

- 1 Introduction
- 2 Variable background
 - Results
 - Idea of proof
- 3 Euler-Poisson alignment system
 - Model
 - Results

Motivation to CTC

Pressureless Euler equation,

$$\rho_t + (\rho u)_x = 0, \quad \mathbb{R} \times (0, \infty),$$

$$u_t + uu_x = 0,$$

with $u(0, x) = u_0(x)$.

Motivation to CTC

Pressureless Euler equation,

$$\begin{aligned}\rho_t + (\rho u)_x &= 0, \quad \mathbb{R} \times (0, \infty), \\ u_t + uu_x &= 0,\end{aligned}$$

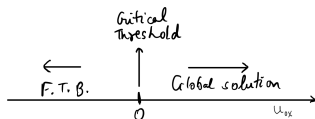
with $u(0, x) = u_0(x)$. Using method of characteristics,

$$u_x(t, X(t; \alpha)) = \frac{u_{0x}(\alpha)}{1 + tu_{0x}(\alpha)}, \quad \alpha \in \mathbb{R}.$$

Hence, if for some x^* , $u_{0x}(x^*) < 0$, then

$$\lim_{t \rightarrow t^{*-}} u_{0x} = -\infty, \quad t^* = -\frac{1}{u_{0x}(x^*)}.$$

u_x is bounded for all time if and only if $u_{0x}(x) \geq 0$ for all $x \in \mathbb{R}$.



Criteria of breakdown: $u_x \rightarrow -\infty$ (shock formation) along with $\rho \rightarrow \infty$ (density concentration) at the same time.

Model

A class of 1D Euler-Poisson equations with background and damping:

$$\rho_t + (\rho u)_x = 0, \quad x \in \mathbb{R} \quad (\text{Mass conservation})$$

$$u_t + uu_x + \nu u = -k\phi_x, \quad (\text{Momentum equation})$$

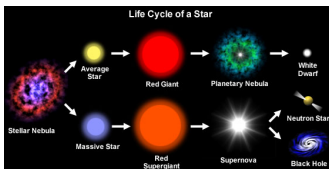
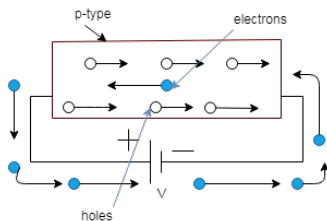
$$-\phi_{xx} = \rho - c, \quad (\text{Poisson equation})$$

with initial conditions $(\rho_0(x) \geq 0, u_0(x)) \in C_b^1(\mathbb{R}) \times C_b^1(\mathbb{R})$.

- ν is the damping constant.
- c is the background term which may be a constant or vary with space.
- k signifies property of underlying forcing: repulsive ($k > 0$) or attractive ($k < 0$).

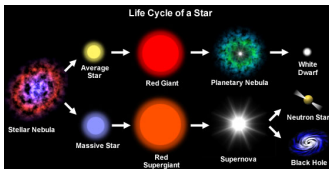
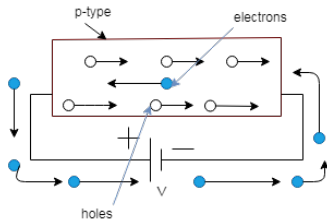
Applications

- Modeling charge flows in semiconductors, cosmological waves and evolution of stars.



Applications

- Modeling charge flows in semiconductors, cosmological waves and evolution of stars.



Following are some of the many researchers having extensively studied regularity of Euler-Poisson systems:

- Hailiang Liu
- Eitan Tadmor
- Alexander Kiselev

Critical Threshold Phenomena

Question: Find a curve in the phase space of initial configuration which precisely delineates the global solution/finite-time-breakdown regions.

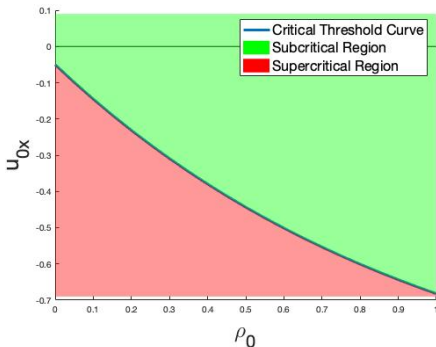


Figure: Idea of threshold curve in Euler Poisson systems.

Constant background

For $k > 0$ (repulsive forcing), there are 3 separate cases,

- ① $\nu > 2\sqrt{kc}$, strong damping (No oscillations),
- ② $\nu < 2\sqrt{kc}$, weak damping (Oscillatory solutions), and
- ③ $\nu = 2\sqrt{kc}$, borderline damping (No oscillations).

Constant background

For $k > 0$ (repulsive forcing), there are 3 separate cases,

- ① $\nu > 2\sqrt{kc}$, strong damping (No oscillations),
- ② $\nu < 2\sqrt{kc}$, weak damping (Oscillatory solutions), and
- ③ $\nu = 2\sqrt{kc}$, borderline damping (No oscillations).

For $k < 0$ (attractive forcing),

- Solutions are of a single type without any oscillations.

Repulsive forcing and constant background

Theorem 1 (B-Liu '20, M3AS)

Let $k > 0$ and $\nu < 2\sqrt{kc}$ (*weak damping*). There exists a unique solution $\rho, u \in C^1(\mathbb{R} \times (0, \infty))$ iff $\forall x \in \mathbb{R}$,

$$(\rho_0(x), u_{0x}(x)) \in \{(\rho, d) : -\rho Q_1(1/\rho) < d < -\rho Q_2(s^* - 1/\rho), \rho \in (1/s^*, \infty)\},$$

where $s^* > 0$ is uniquely determined, and $Q_1 : [0, s^*] \rightarrow \mathbb{R}^+ \cup \{0\}$ is a continuous function satisfying

$$\frac{dQ_1}{ds} = \nu + \frac{k}{Q_a}(1 - cs), \quad Q_1(0) = 0,$$

and $Q_2 : [0, s^*] \rightarrow \mathbb{R}^- \cup \{0\}$ is another continuous function satisfying

$$\frac{dQ_2}{ds} = -\nu + \frac{k}{Q_2}(c(s^* - s) - 1), \quad Q_2(0) = 0.$$

Repulsive forcing and constant background

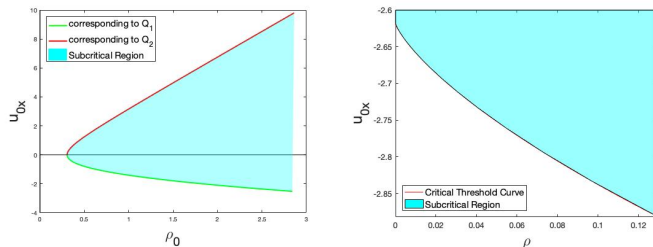


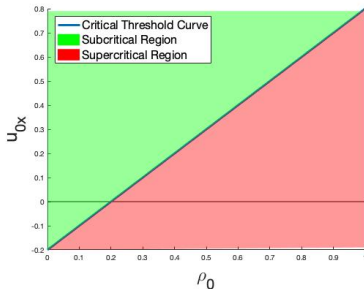
Figure: Left: Weak damping ($\nu < 2\sqrt{kc}$). Right: Strong damping ($\nu > 2\sqrt{kc}$).

Attractive forcing

Theorem 2

Let $k < 0$. Then there exists a unique solution $\rho, u \in C^1(\mathbb{R} \times (0, \infty))$ iff $\forall x \in \mathbb{R}$,

$$(\rho_0(x), u_{0x}(x)) \in \left\{ (\rho, d) : d \geq \left(\frac{\nu + \sqrt{\nu^2 - 4kc}}{2c} \right) (\rho - c) \right\}.$$



Variable background

- **Question:** What if $c = c(x)$?

$$\rho_t + (\rho u)_x = 0,$$

$$u_t + uu_x + \nu u = -k\phi_x,$$

$$-\phi_{xx} = \rho - c(x),$$

with $\rho_0 \geq 0$, $u_0 \in C^1(\mathbb{T})$.

Variable background

- **Question:** What if $c = c(x)$?

$$\rho_t + (\rho u)_x = 0,$$

$$u_t + uu_x + \nu u = -k\phi_x,$$

$$-\phi_{xx} = \rho - c(x),$$

with $\rho_0 \geq 0$, $u_0 \in C^1(\mathbb{T})$.

- Not just more general but physically more meaningful too.

Variable background

- **Question:** What if $c = c(x)$?

$$\rho_t + (\rho u)_x = 0,$$

$$u_t + uu_x + \nu u = -k\phi_x,$$

$$-\phi_{xx} = \rho - c(x),$$

with $\rho_0 \geq 0$, $u_0 \in C^1(\mathbb{T})$.

- Not just more general but physically more meaningful too.
- We will consider $k < 0$ and $c_1 \leq c(x) \leq c_2$.

Variable background

- **Question:** What if $c = c(x)$?

$$\rho_t + (\rho u)_x = 0,$$

$$u_t + uu_x + \nu u = -k\phi_x,$$

$$-\phi_{xx} = \rho - c(x),$$

with $\rho_0 \geq 0, u_0 \in C^1(\mathbb{T})$.

- Not just more general but physically more meaningful too.
- We will consider $k < 0$ and $c_1 \leq c(x) \leq c_2$.
- Criteria of breakdown: At time t^* of breakdown,

$$-\lim_{t \uparrow t^*} u_x(\cdot, t) = \lim_{t \uparrow t^*} \rho(\cdot, t) = \infty.$$

- Therefore, aim is to bound ρ from above and u_x from below.

Variable Background

- 1 Introduction
- 2 Variable background
 - Results
 - Idea of proof
- 3 Euler-Poisson alignment system
 - Model
 - Results

Global solution

Theorem 3 (B-Liu '20, Phys D)

If for all $x \in \mathbb{T}$,

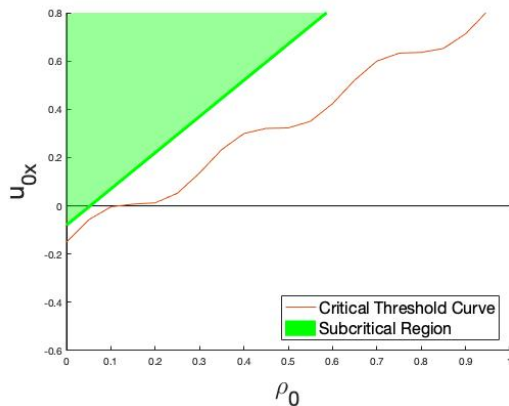
$$(\rho_0(x), u_{0x}(x)) \in \left\{ (\rho, d) : d > \frac{\lambda_1}{c_1}(\rho - c_1) \right\},$$

then there exists a unique global-in-time solution, $\rho, u \in C^1((0, \infty) \times \mathbb{T})$. Moreover,

$$\begin{aligned} \|\rho(t, \cdot)\|_\infty &\leq \|\rho_0\|_\infty e^{\lambda_1 t}, \\ -\lambda_1 &\leq u_x(t, \cdot) \leq \text{constant}(c_2, \nu, \|u_{0x}\|_\infty). \end{aligned}$$

$$c_1 = \min c, \quad c_2 = \max c,$$

$$\lambda_1 = \frac{\nu + \sqrt{\nu^2 - 4kc_1}}{2}.$$



Finite-time-breakdown

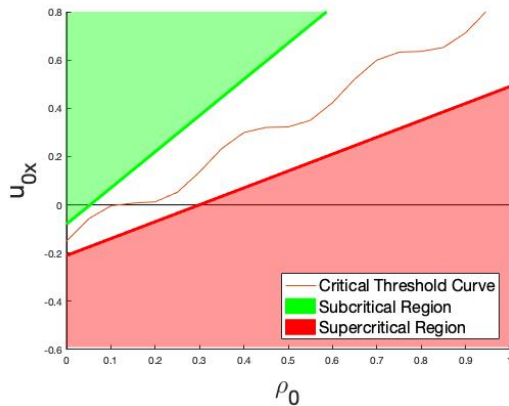
Theorem 4 (B-Liu '20, Phys D)

If $\exists x_0 \in \mathbb{T}$ such that

$$u_{0x}(x_0) < \left(\frac{\nu + \sqrt{\nu^2 - 4kc_2}}{2c_2} \right) (\rho_0(x_0) - c_2),$$

then $\exists (t^*, x^*)$ such that

$$\lim_{t \uparrow t^*} u_x(t, x^*) = - \lim_{t \uparrow t^*} \rho(t, x^*) = -\infty.$$



Preliminaries

Let $u_x := d$. Using method of characteristics, EP system can be reduced to ODE system:

$$\begin{aligned}\rho' &= -\rho d, \\ d' &= -d^2 - \nu d + k(\rho - c(x(t))),\end{aligned}$$

Initial conditions:

$$\rho(0) = \rho_0(\alpha), \quad d(0) = d_0(\alpha) = u_{0x}(\alpha),$$

for $\alpha \in \mathbb{T}$.

Tools: Auxiliary system

- Introduce an auxiliary system of equations:

$$\begin{aligned}\eta' &= -\eta\xi, \\ \xi' &= -\xi^2 - \nu\xi + k\eta - k\gamma.\end{aligned}$$

$\gamma \geq 0$ is parameter. Initial conditions, $\eta(0), \xi(0)$, to be chosen appropriately later.

Proposition 2.1

If

$$\xi(0) \geq \left(\frac{\nu + \sqrt{\nu^2 - 4k\gamma}}{2\gamma} \right) (\eta(0) - \gamma),$$

then (η, ξ) exist for all time and,

$$\xi(t) \geq \left(\frac{\nu + \sqrt{\nu^2 - 4k\gamma}}{2\gamma} \right) (\eta(t) - \gamma).$$

Otherwise, $\exists t^$ such that*

$$\lim_{t \uparrow t^*} \eta(t) = - \lim_{t \uparrow t^*} \xi(t) = \infty.$$

Sketch of proof

$$\eta(t) = \eta(0)e^{-\int_0^t \xi d\tau}.$$

- As long as ξ exists, η maintains sign. Hence, $\eta(0) = 0 \equiv \eta(t)$ can be handled separately.
- For $\eta(0) > 0 \implies \eta(t) > 0$ for all time. An eventual transformation of variables:

$$r = \frac{\xi}{\eta}, \quad s = \frac{1}{\eta},$$

enables us to derive the proposition.

- This crucial transformation has also been used by other authors (C. Tan, A. Kiselev,...) to analyze at CT for various class of Euler-Poisson systems.

Sketch of proof

$$\gamma s = 1 - \frac{r}{\lambda}, \quad \lambda = \frac{\nu + \sqrt{\nu^2 - 4k\gamma}}{2\gamma}.$$

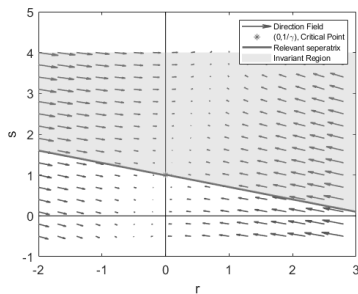


Figure: $r - s$ phase potrait.

Tools: Comparison Lemma

Lemma 5

As long as ρ, d, η, ξ exist, we have

(i) For $\gamma = \min c(x)$: If $\rho(0) < \eta(0)$ and $d(0) > \xi(0)$, then

$$\rho(t) < \eta(t), \quad d(t) > \xi(t).$$

(ii) For $\gamma = \max c(x)$: If $\rho(0) > \eta(0)$ and $d(0) < \xi(0)$, then

$$\rho(t) > \eta(t), \quad d(t) < \xi(t).$$

Comparison Lemma

- Proved by a contradiction argument.
- Sign of k plays a vital role.
- A comparison principle for $k > 0$ cannot be easily derived due to oscillatory solutions. This is our current project in collaboration with Dr.Changhui Tan (U of S Carolina).

Proof of Theorem

- If $d(0) > \lambda_1(\rho(0) - c_1)$

Proof of Theorem

- If $d(0) > \lambda_1(\rho(0) - c_1)$, we can choose $\eta(0) > \rho(0)$ and $\xi(0) < d(0)$ such that

$$d(0) > \xi(0) \geq \lambda_1(\eta(0) - c_1) > \lambda_1(\rho(0) - c_1).$$

From Proposition for auxiliary system,

$$\xi(t) \geq \lambda_1(\eta(t) - c_1)$$

Proof of Theorem

- If $d(0) > \lambda_1(\rho(0) - c_1)$, we can choose $\eta(0) > \rho(0)$ and $\xi(0) < d(0)$ such that

$$d(0) > \xi(0) \geq \lambda_1(\eta(0) - c_1) > \lambda_1(\rho(0) - c_1).$$

From comparison Lemma

$$d(t) > \xi(t) \geq \lambda_1(\eta(t) - c_1) > \lambda_1(\rho(t) - c_1)$$

Proof of Theorem

- If $d(0) > \lambda_1(\rho(0) - c_1)$, we can choose $\eta(0) > \rho(0)$ and $\xi(0) < d(0)$ such that

$$d(0) > \xi(0) \geq \lambda_1(\eta(0) - c_1) > \lambda_1(\rho(0) - c_1).$$

Putting together,

$$d(t) > \xi(t) \geq \lambda_1(\eta(t) - c_1) > \lambda_1(\rho(t) - c_1).$$

Euler-Poisson alignment systems

- 1 Introduction
- 2 Variable background
 - Results
 - Idea of proof
- 3 Euler-Poisson alignment system
 - Model
 - Results

EPA system

Euler Poisson system with alignment induced by kernel ψ :

$$\rho_t + (\rho u)_x = 0, \quad x \in \mathbb{T}$$

$$u_t + uu_x + \nu u = -k\phi_x + \psi * (\rho u) - u\psi * \rho,$$

$$-\phi_{xx} = \rho - c(x).$$

EPA system

Euler Poisson system with alignment induced by kernel ψ :

$$\rho_t + (\rho u)_x = 0, \quad x \in \mathbb{T}$$

$$\begin{aligned} u_t + uu_x + \nu u &= -k\phi_x + \psi * (\rho u) - u\psi * \rho, \\ -\phi_{xx} &= \rho - c(x). \end{aligned}$$

Properties of ψ :

- $\psi(x) = \psi(-x)$, $x > 0$ (Symmetric),
- $\psi(x+1) = \psi(x)$ (Periodic),
- $|\psi(x) - \psi(y)| \leq K|x - y|$ (Lipschitz continuous).

Tools

- The comparison lemma does not work directly.
- However, a change of variables helps:

$$w = \frac{u_x + \nu + \psi * \rho}{\rho}, \quad s = \frac{1}{\rho}.$$

- The ODE system along characteristic is:

$$w' = k - kcs$$

$$s' = w - (\nu + \psi * \rho)s.$$

- The auxiliary system has **two** parameters: β and γ :

$$p' = k - k\gamma q$$

$$q' = p - \beta q.$$

Global existence

Theorem 6 (B-Liu '20, Phys D)

If for all $x \in \mathbb{T}$,

$$u_{0x}(x) > \lambda_M \rho_0(x) - \theta_1 - \nu - \psi * \rho_0(x),$$

then there exists a unique global-in-time solution, $\rho, u \in C^1((0, \infty) \times \mathbb{T})$.
Furthermore,

$$\begin{aligned} \|\rho(t, \cdot)\|_\infty &\leq \|\rho_0\|_\infty e^{\lambda_M t}, \\ -\lambda_M &\leq u_x(t, \cdot) \leq \text{constant}(\max u_{0x}, \nu, c_2, \psi_M, \psi_m). \end{aligned}$$

$$\psi_m = \min \psi, \quad \psi_M = \max \psi, \quad c_1 = \min c, \quad c_2 = \max c,$$

$$\lambda_M = \frac{(\nu + \psi_M) + \sqrt{(\nu + \psi_M)^2 - 4kc_1}}{2c_1},$$

$$\theta_1 = \frac{-(\nu + \psi_M) + \sqrt{(\nu + \psi_M)^2 - 4kc_1}}{2c_1}.$$

Finite time breakdown

Theorem 7 (B-Liu '20, Phys D)

If $\exists x_0 \in \mathbb{T}$ such that

$$u_{0x}(x_0) < \lambda_m \rho_0(x_0) - \theta_2 - \nu - \psi * \rho_0(x_0),$$

then $\exists(t^*, x^*)$ such that $\lim_{t \uparrow t^*} u_x(t, x^*) = -\infty$.

$$\lambda_m = \frac{(\nu + \psi_m) + \sqrt{(\nu + \psi_m)^2 - 4kc_2}}{2c_2},$$

$$\theta_2 = \frac{-(\nu + \psi_m) + \sqrt{(\nu + \psi_m)^2 - 4kc_2}}{2c_2}.$$

Thank You!
Questions?